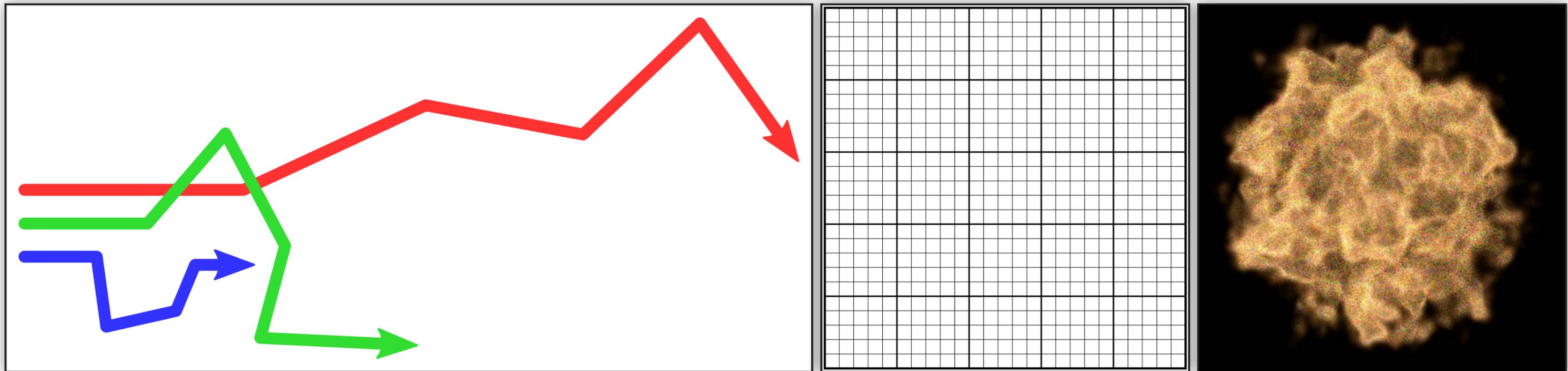


**Monte Carlo methods for volumetric light transport
simulation
STAR at EG 2018
Advanced methods and acceleration data structures**

Johannes Hanika
Lehrstuhl für Computergrafik
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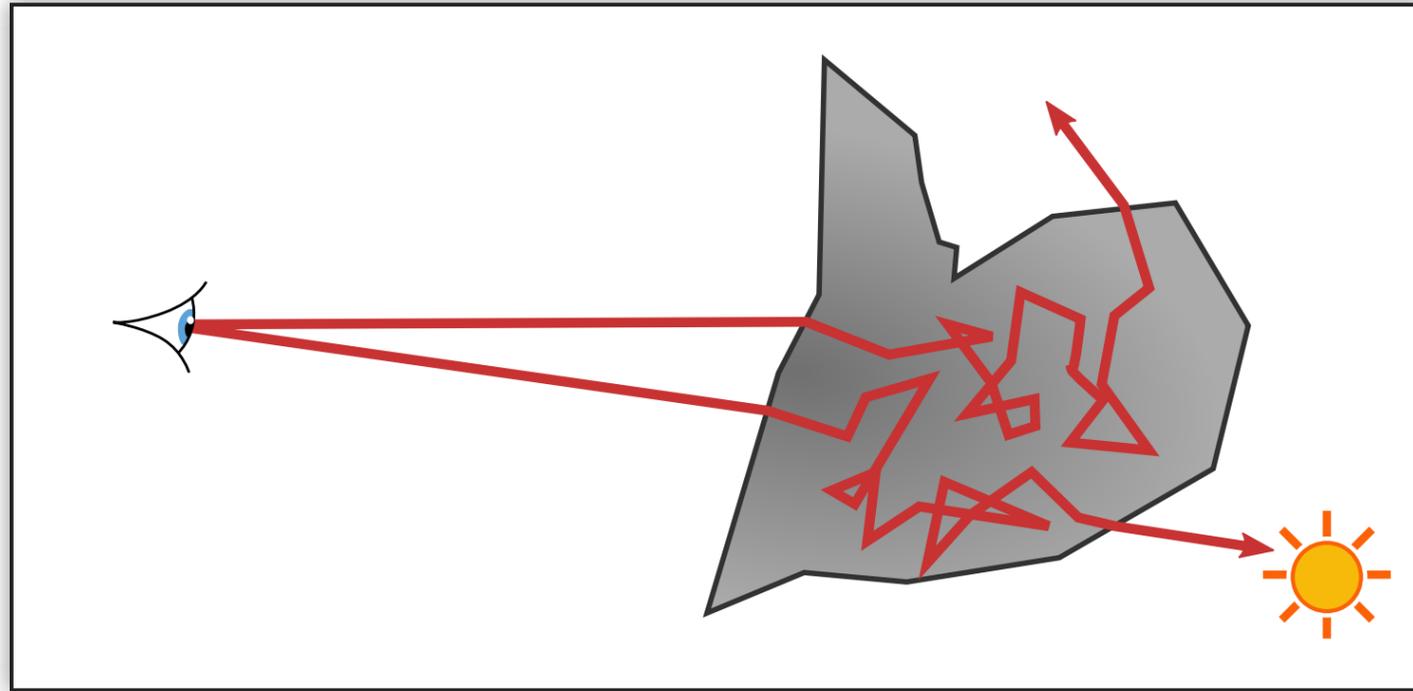
contents

- ▶ selection of advanced methods:
 - ▶ Dwivedi sampling / zero variance random walks
 - ▶ spectral tracking
- ▶ acceleration data structures
 - ▶ for regular tracking
 - ▶ inside these: null collision based
- ▶ emissive media



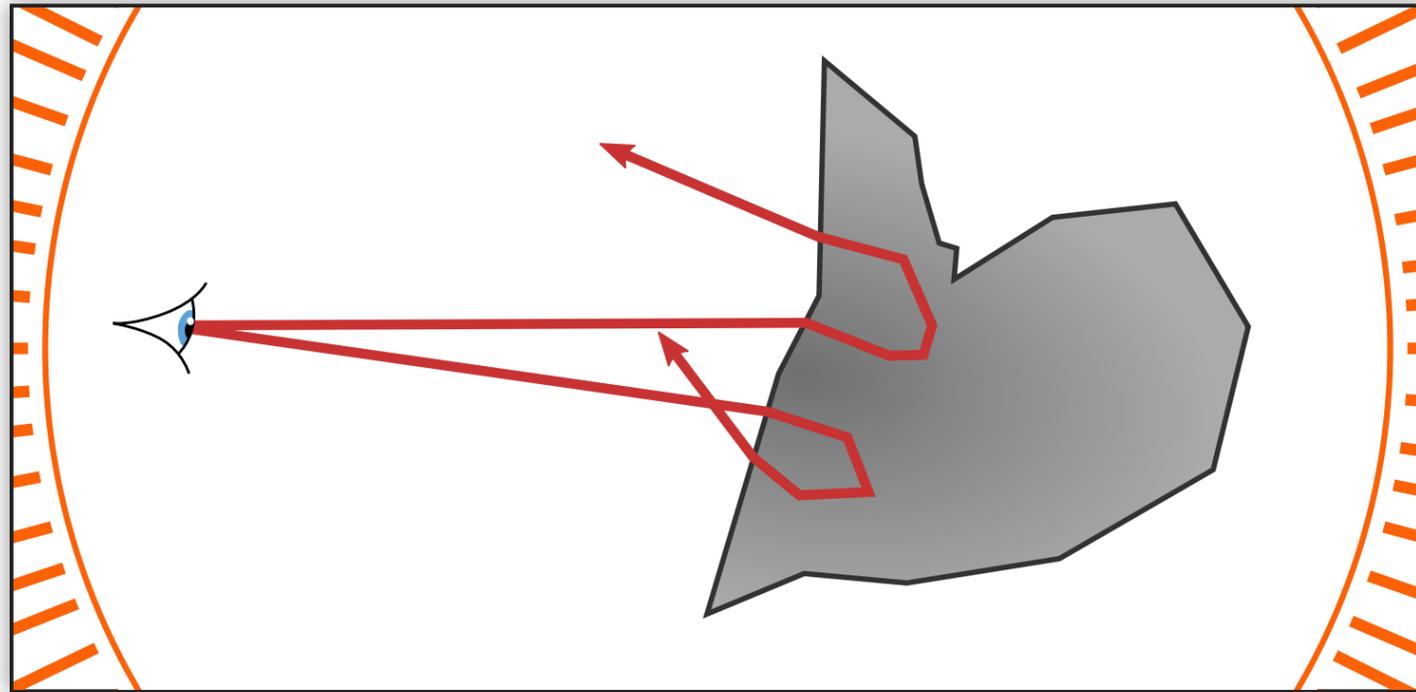
Dwivedi sampling

- ▶ regular path tracing random walk
- ▶ tends to get lost inside a **volume bounded by a shape**



Dwivedi sampling

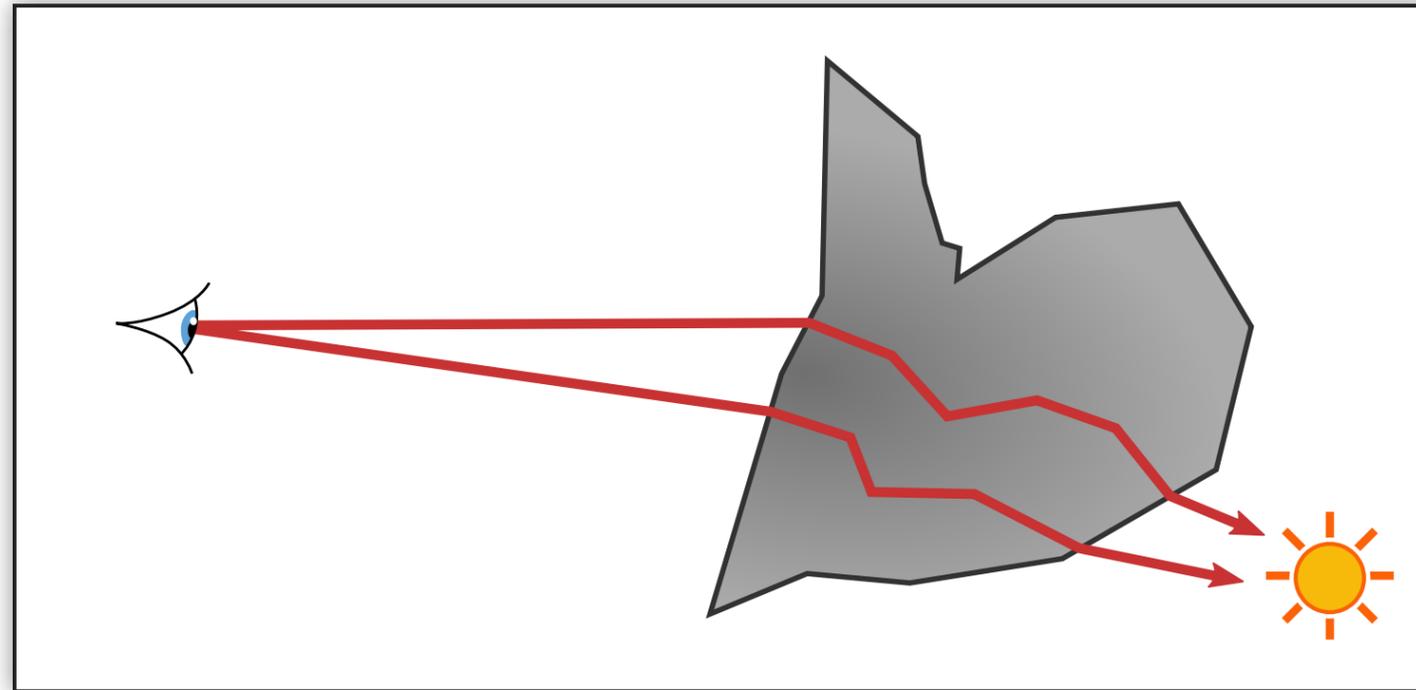
- ▶ random walk biased to exit **bounded volume** as quickly as possible
- ▶ assumes constant illumination from the outside [Kd14]



- ▶ assume **homogeneous slab** with **isotropic** phase function
- ▶ approximate closed-form solution of transport using this simplified setting
- ▶ known as **zero-variance theory** (term may be a bit bold)

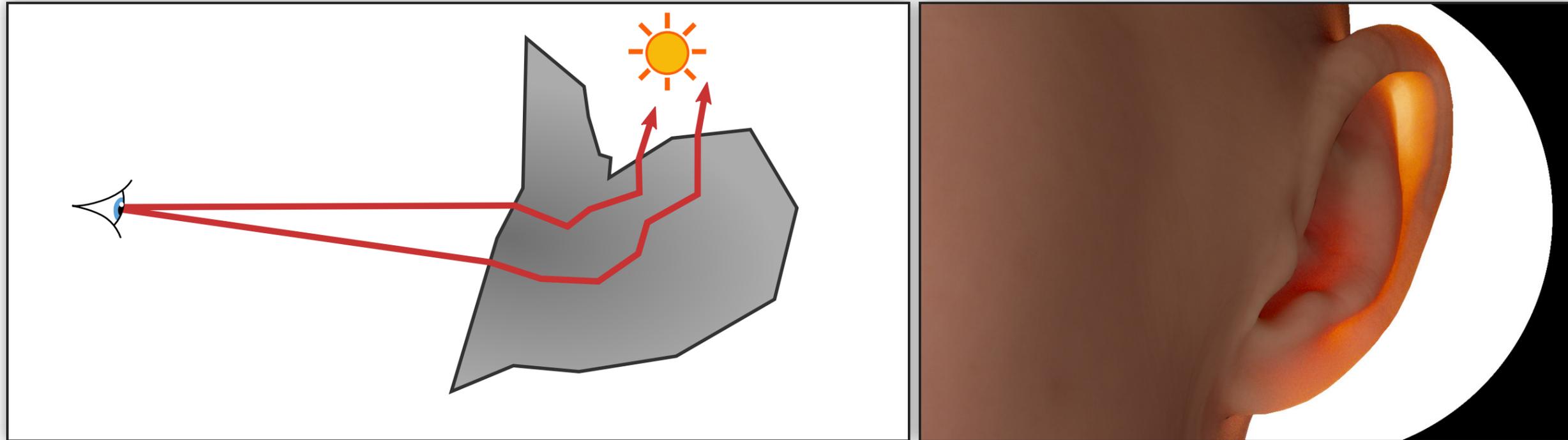
Dwivedi sampling

- ▶ random walk biased towards light source
- ▶ aims to exit towards light [MHD16]



Dwivedi sampling

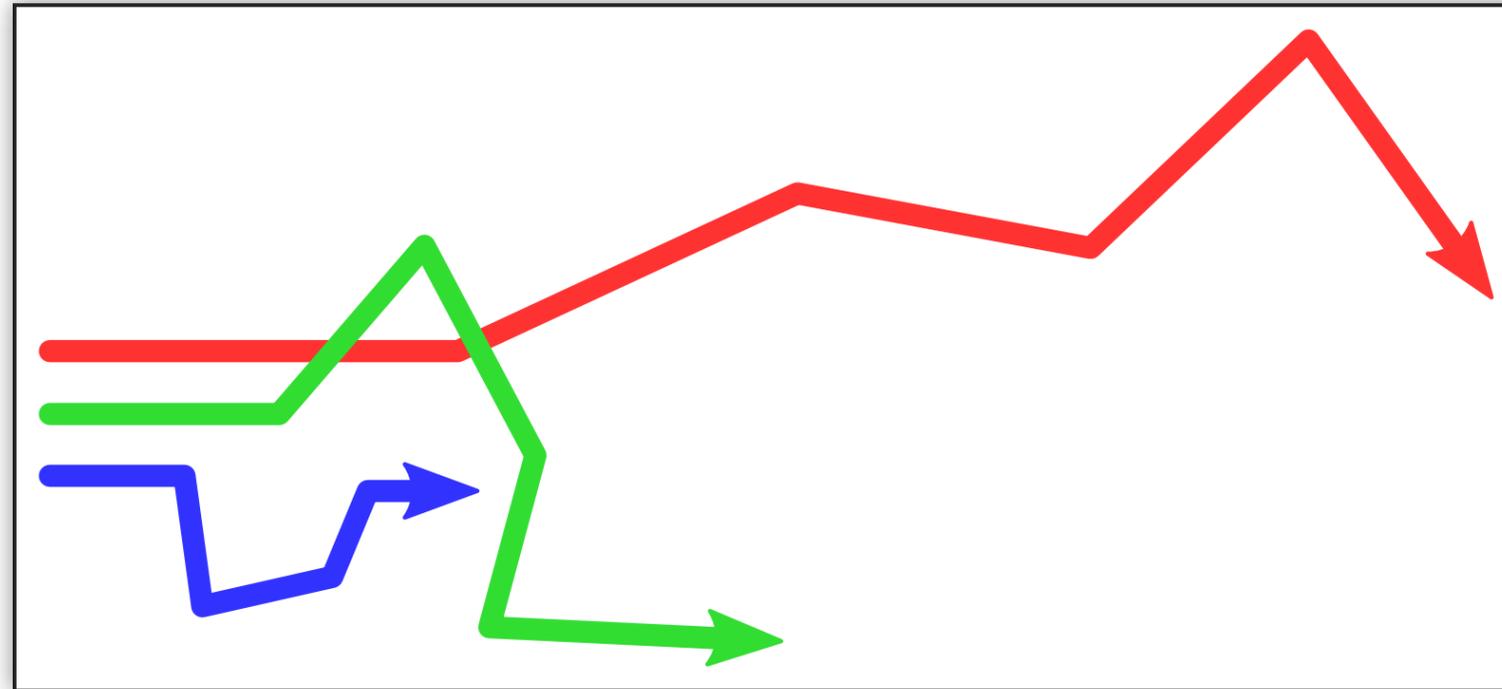
- ▶ random walk biased towards light source
- ▶ aims to exit towards light [MHD16]



- ▶ achieved by **biasing the PDF** to sample direction and distance
- ▶ estimator remains unbiased!

spectral tracking

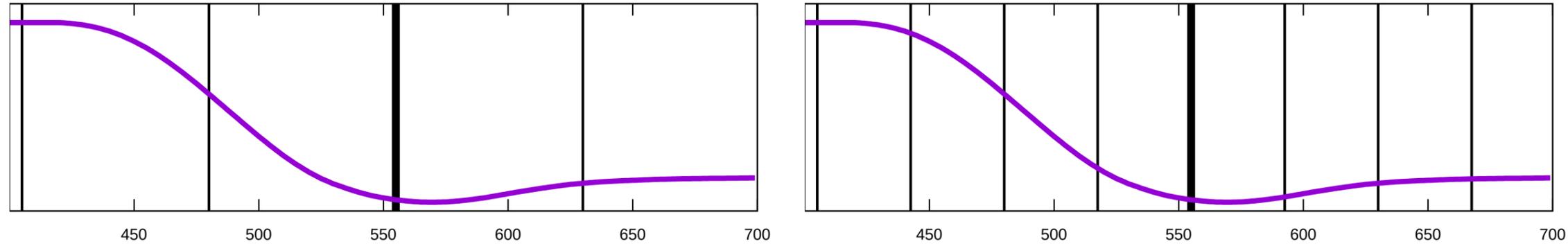
- ▶ another problem with skin: chromatic media
 - ▶ collision coefficients μ depend on wavelength λ
 - ▶ for instance free flight distance much longer for long wavelengths:



- ▶ makes path invalid for different wavelength?
- ▶ can we still exploit coherence?

spectral tracking via MIS

▶ hero wavelength sampling [WND*14]



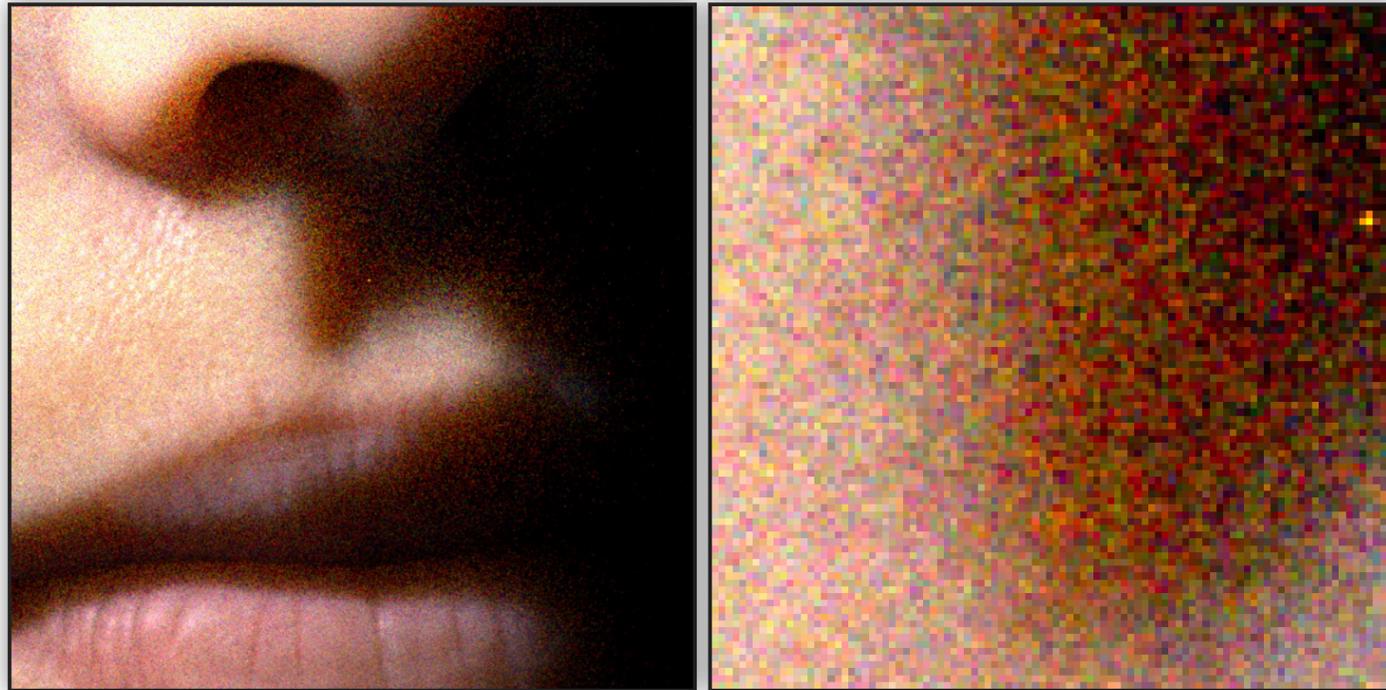
- ▶ sample perfectly for one single wavelength λ_0
- ▶ evaluate path for a stratified set of wavelengths λ_i at the same time
- ▶ optimally weighted combination via **MIS (balance heuristic)**
 - ▶ limited to **regular tracking** because it requires explicit evaluation of PDF

$$\frac{f(\bar{\mathbf{x}}, \lambda_i)}{\sum_j p(\bar{\mathbf{x}}, \lambda_j)}$$

spectral tracking via MIS

image comparison 64spp

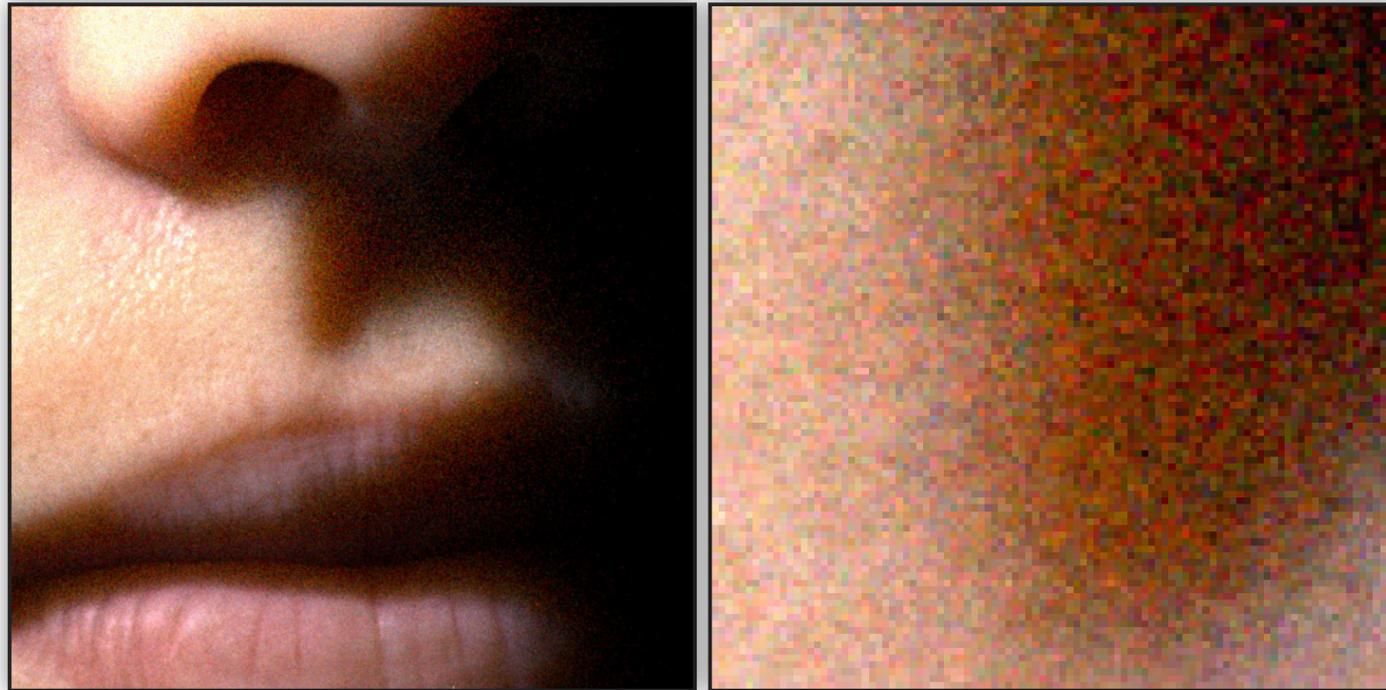
- ▶ skin material with 1 wavelength



spectral tracking via MIS

image comparison 64spp

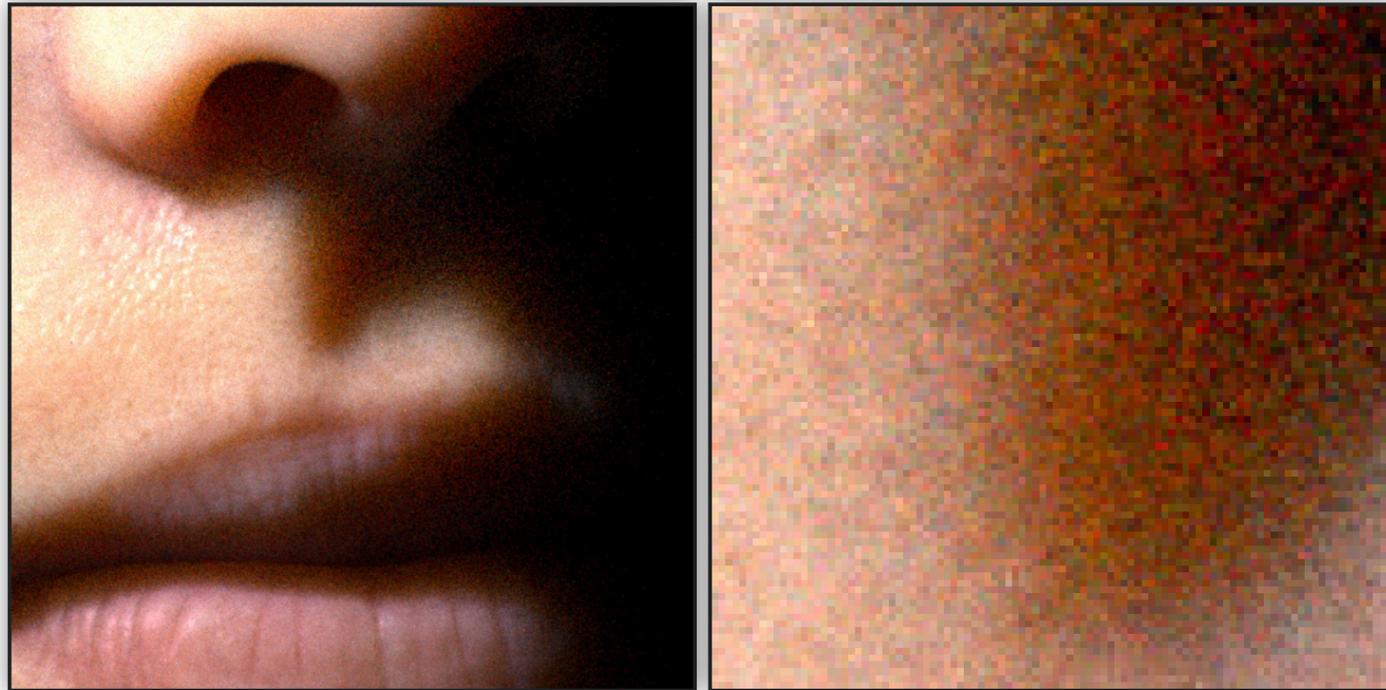
- ▶ skin material with 4 wavelengths (SSE)



spectral tracking via MIS

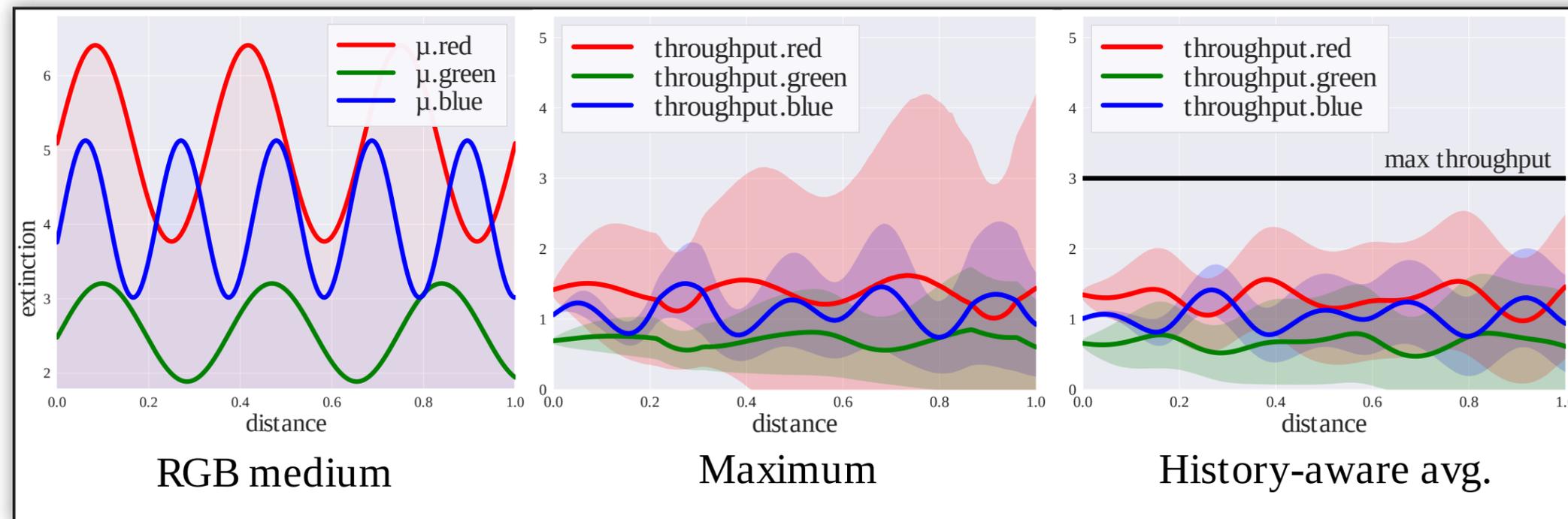
image comparison 64spp

- ▶ skin material with 8 wavelengths (AVX)



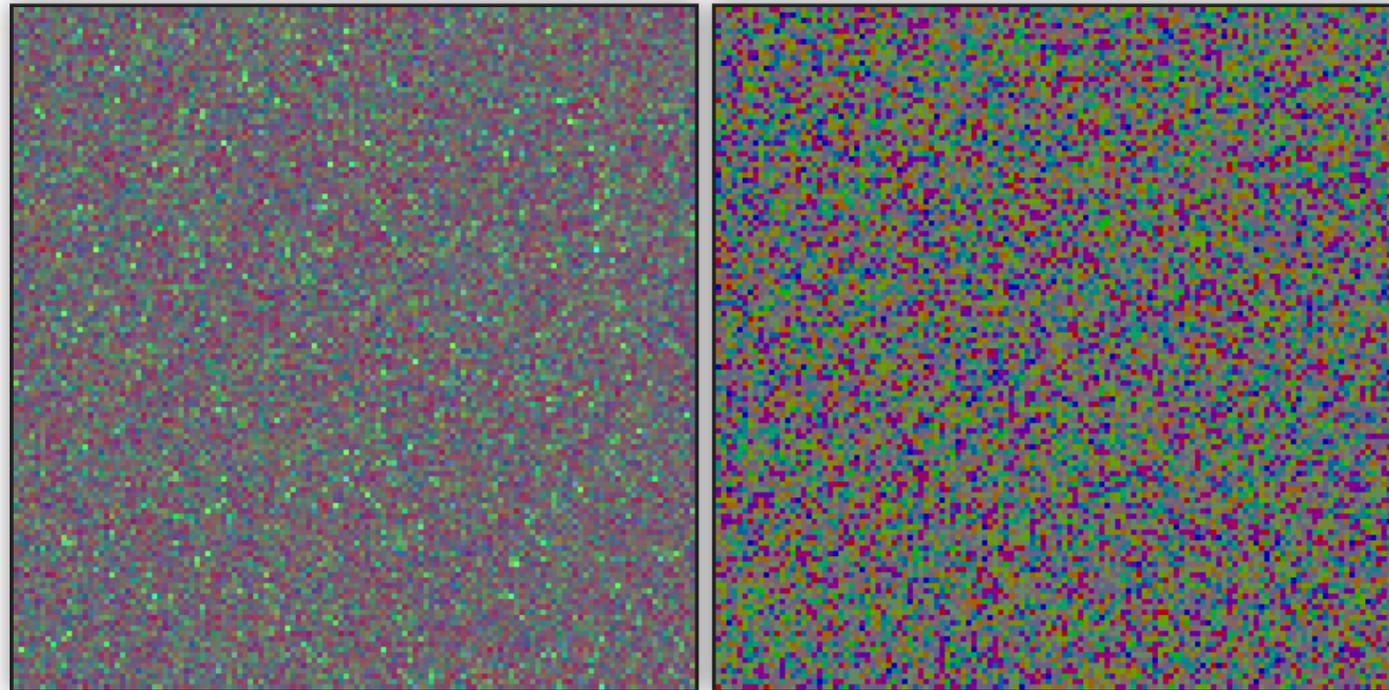
spectral tracking without PDF [KHLN17]

- ▶ sample by common majorant $\bar{\mu}$
- ▶ how do decide for null collision, scattering, or absorption?
- ▶ probability according to $\mu_n(\lambda)$, $\mu_s(\lambda)$, $\mu_a(\lambda)$
 - ▶ pick by maximum over λ_i
 - ▶ pick by average weighted by spectral path throughput history



spectral tracking without PDF [KHLN17]

- ▶ sample by common majorant $\bar{\mu}$
- ▶ how do decide for null collision, scattering, or absorption?
- ▶ probability according to $\mu_n(\lambda)$, $\mu_s(\lambda)$, $\mu_a(\lambda)$
 - ▶ pick by maximum over λ_i
 - ▶ pick by average weighted by spectral path throughput history
 - ▶ results in different noise patterns:



speed!

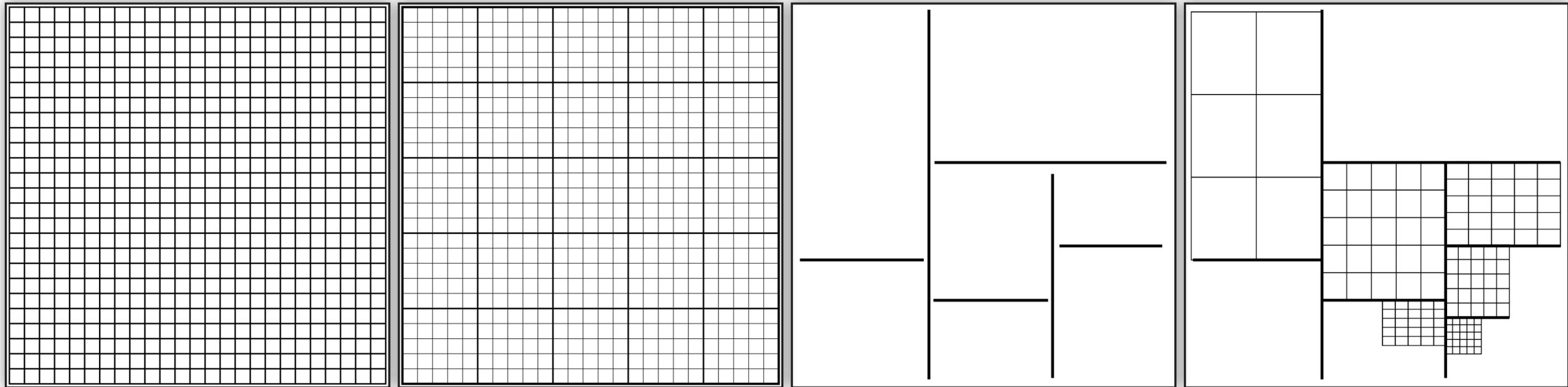
low variance estimators are important

- ▶ but also, in volumes most of the run time is memory fetching



acceleration data structures

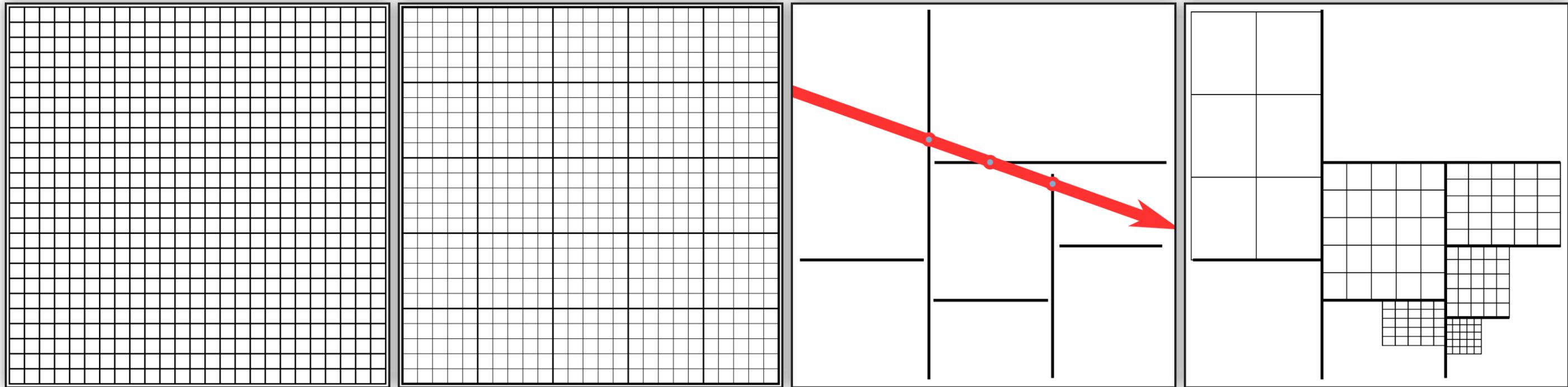
- ▶ grid, super voxels [SKTM11], kd-tree [YIC*11], adaptive blocks



- ▶ adaptivity driven by
 - ▶ pixel footprint / camera tessellation
 - ▶ heterogeneity / variation
- ▶ two-level modelling (super voxel, kd nodes) store majorants $\bar{\mu}$ in coarse blocks

acceleration data structures

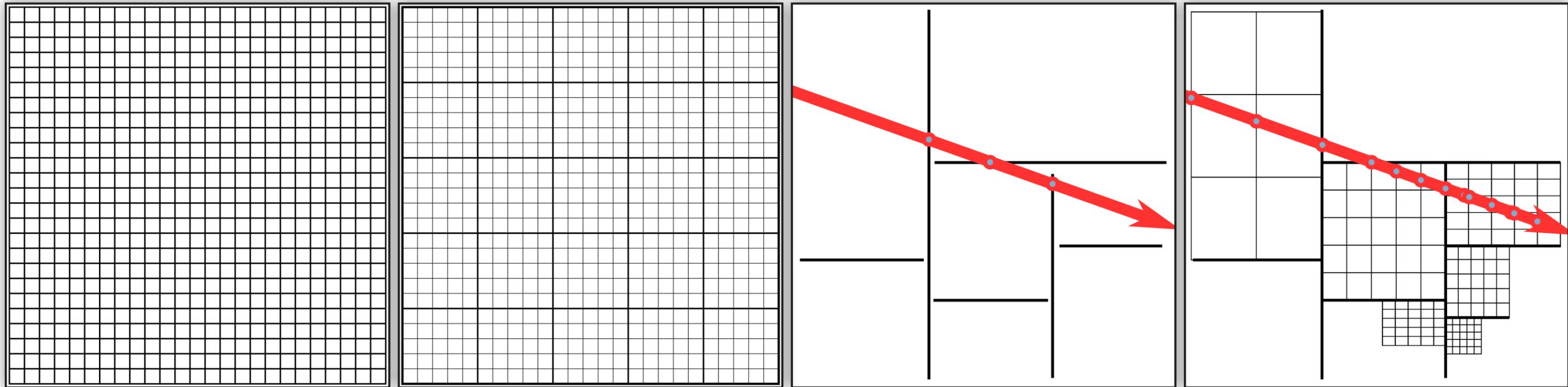
- ▶ grid, super voxels [SKTM11], kd-tree [YIC * 11], adaptive blocks



- ▶ adaptivity driven by
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- ▶ two-level modelling (super voxel, kd nodes) store majorants $\bar{\mu}$ in coarse blocks
 - ▶ perform **regular tracking** on coarse blocks [SKTM11]

acceleration data structures

- ▶ grid, super voxels [SKTM11], kd-tree [YIC * 11], adaptive blocks

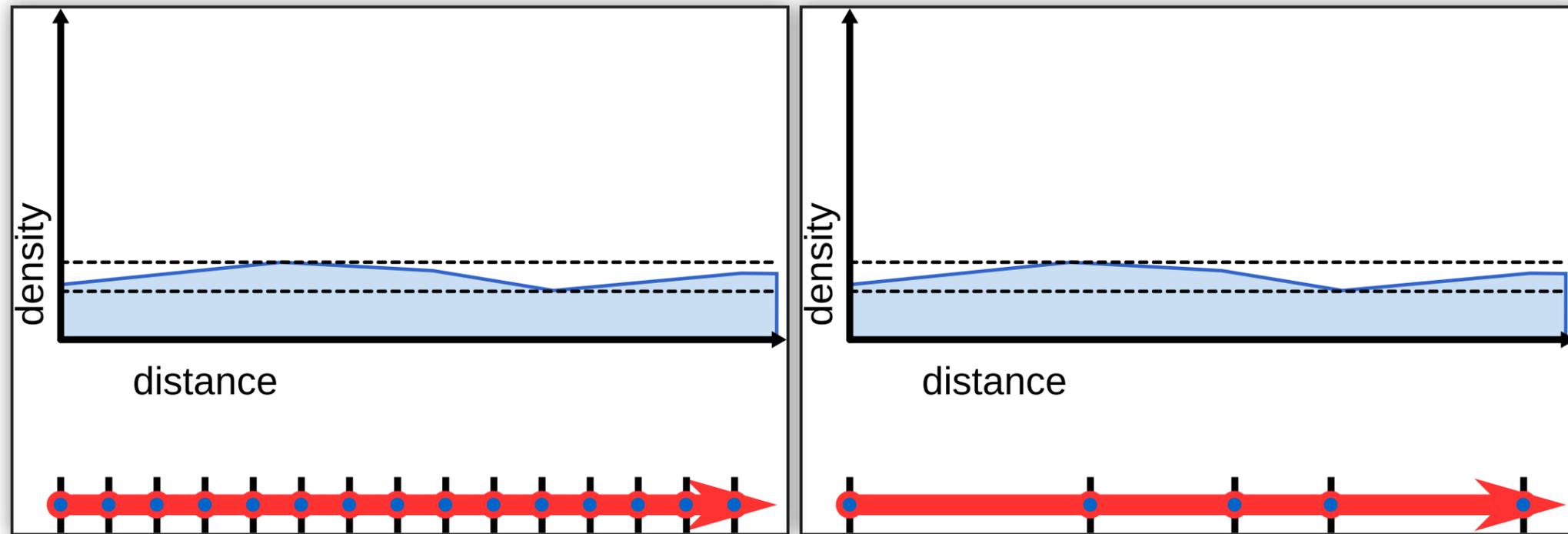


- ▶ adaptivity driven by
 - ▶ pixel footprint / camera tessellation
 - ▶ heterogeneity / variation
- ▶ two-level modelling (super voxel, kd nodes) store majorants $\bar{\mu}$ in coarse blocks
 - ▶ perform **regular tracking** on coarse blocks [SKTM11]
 - ▶ access $\mu_s(\lambda), \mu_a(\lambda)$ on fine levels to sample collision type

acceleration data structures

regular tracking

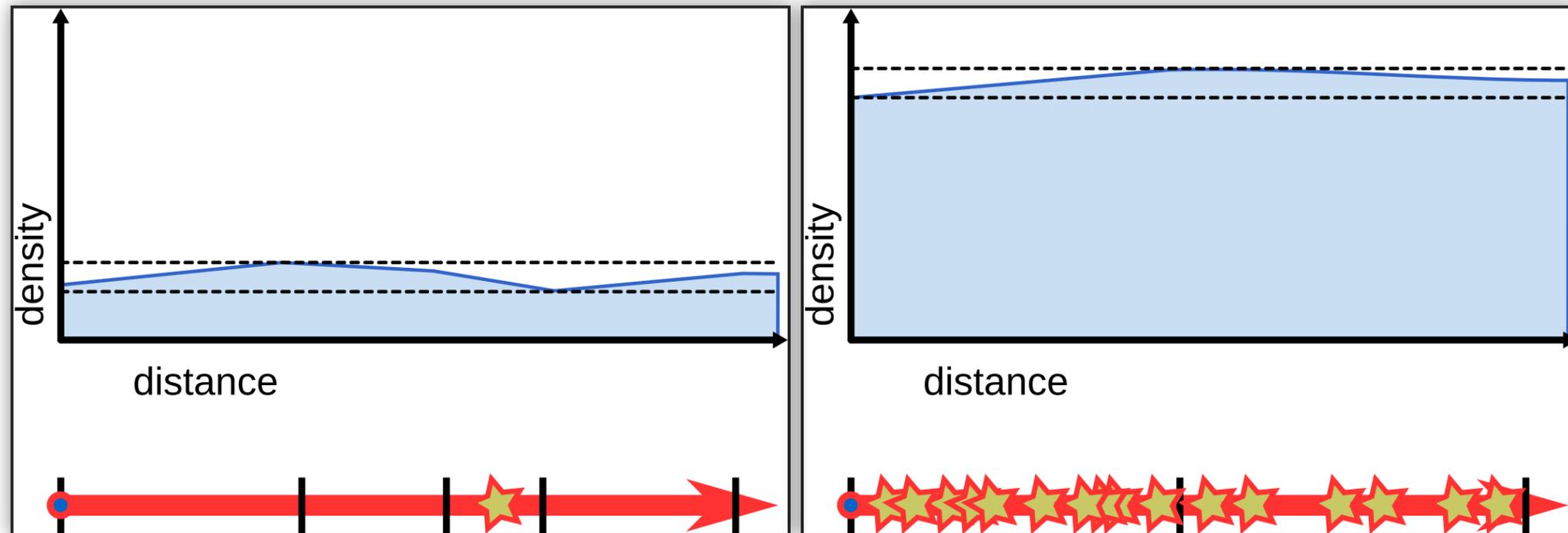
- ▶ needs to step through *every* voxel, bad for fine tessellations
- ▶ well chosen tessellation is a big advantage!



acceleration data structures

null collision-based tracking

- ▶ is independent of tessellation and is efficient in thin media (few events)
- ▶ high number of events in dense media, regardless of tessellation!

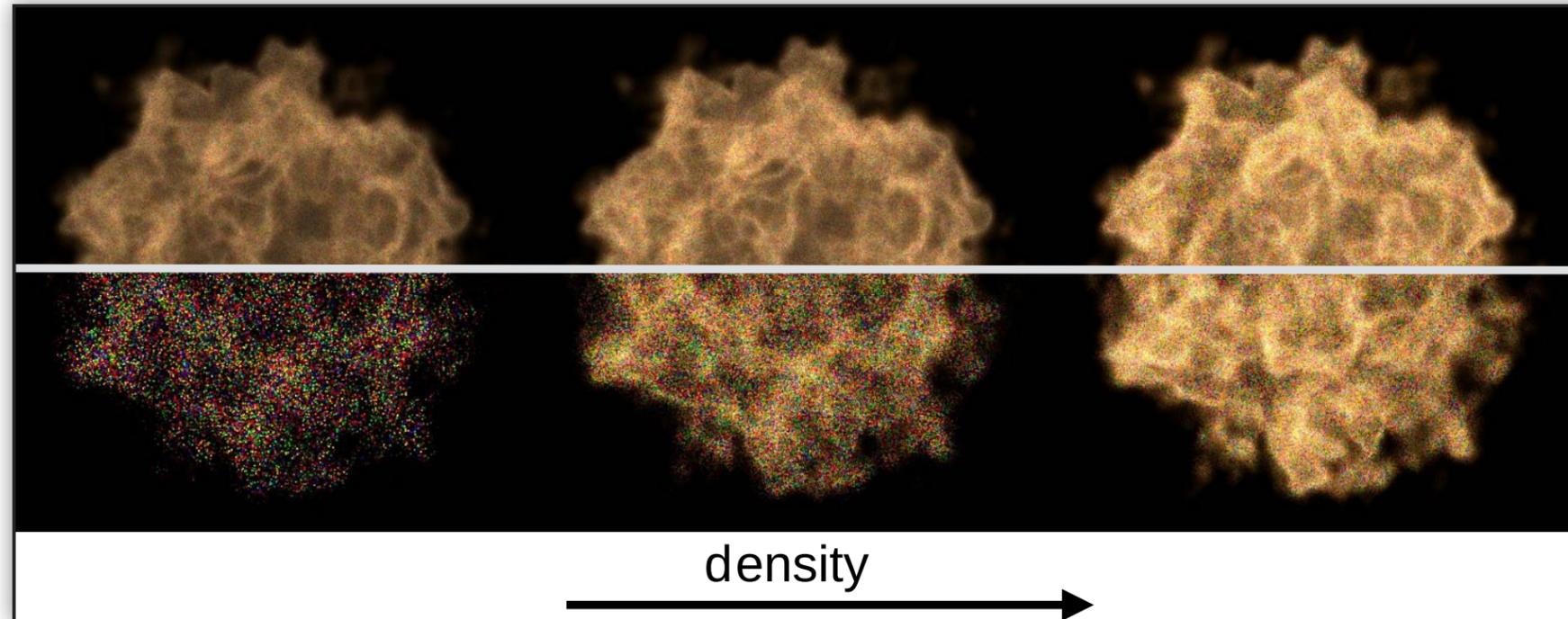


- ▶ accessing the memory within the same voxel is still expensive
- ▶ alleviated by decomposition tracking [KHLN17]
 - ▶ separate μ into sum of coarse and fine, to sample distance pick shortest (and early out!)
 - ▶ also profits full regular tracking

emissive media

thin/dense media make a difference

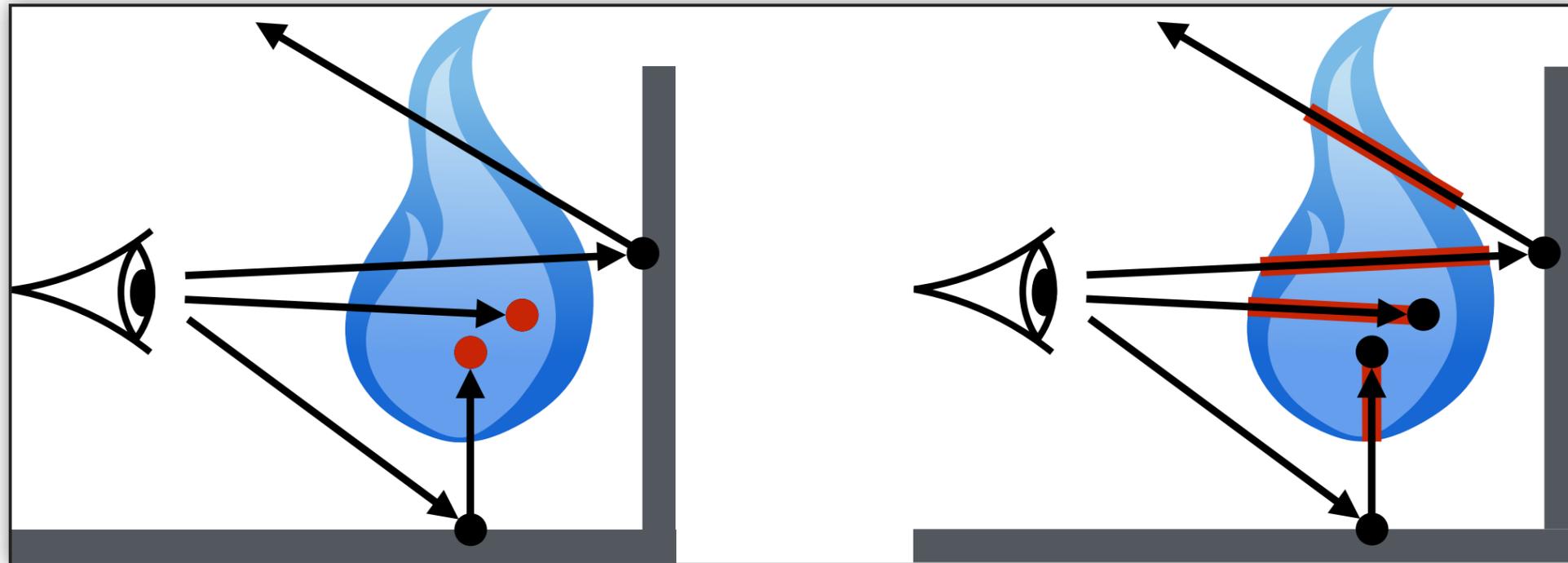
- ▶ no event inside the medium means we cannot pick up emission:



emissive media

thin/dense media make a difference

- ▶ following the idea of beams, collect emission along a ray

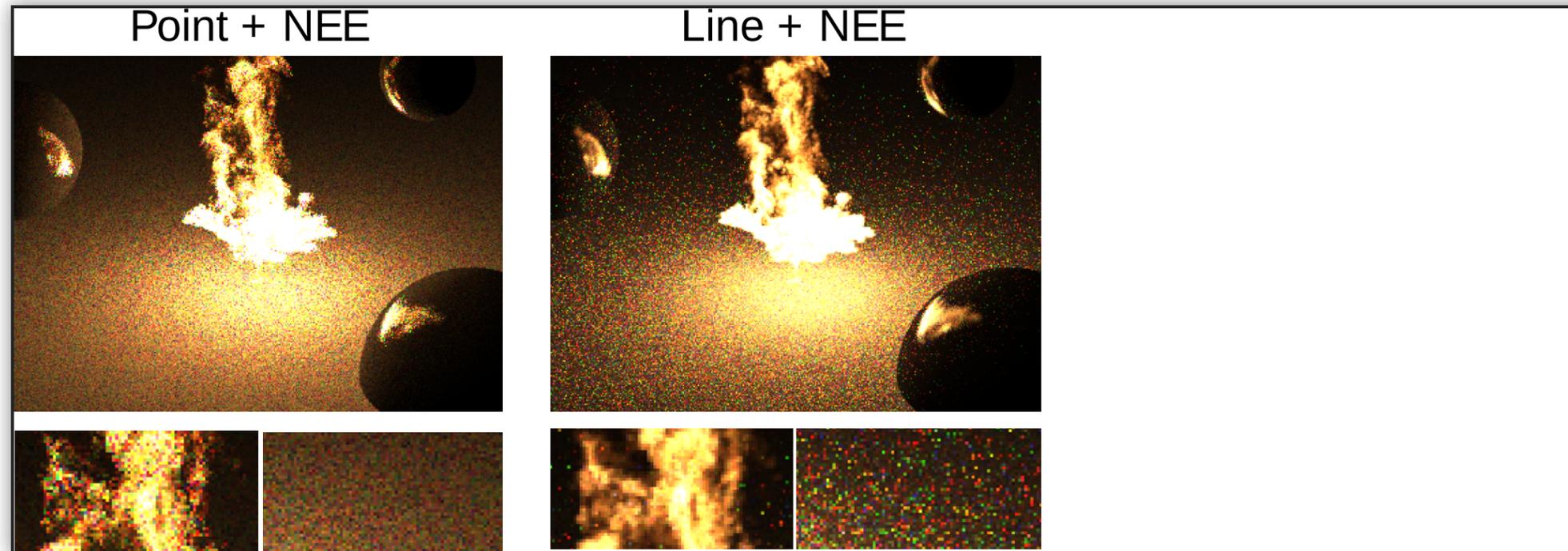


- ▶ particularly well suited for regular tracking, touching all voxels anyways

emissive media

thin/dense media make a difference

- ▶ direct application of MIS with NEE [VH13] introduces noise:

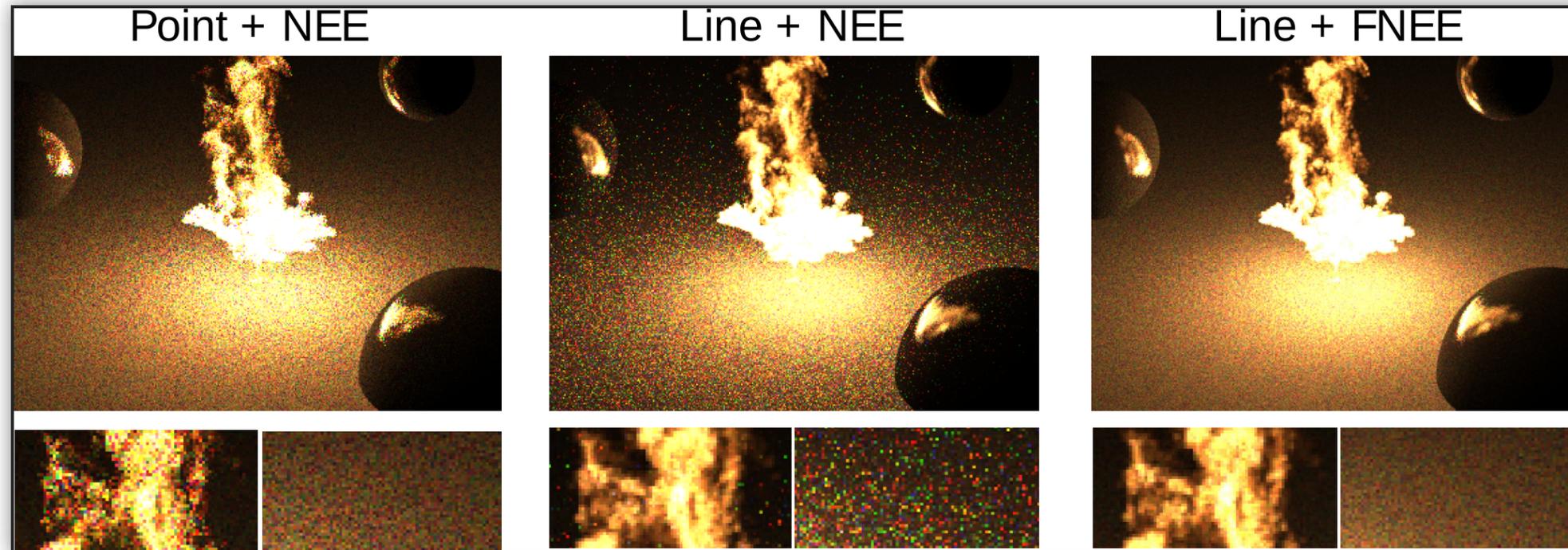


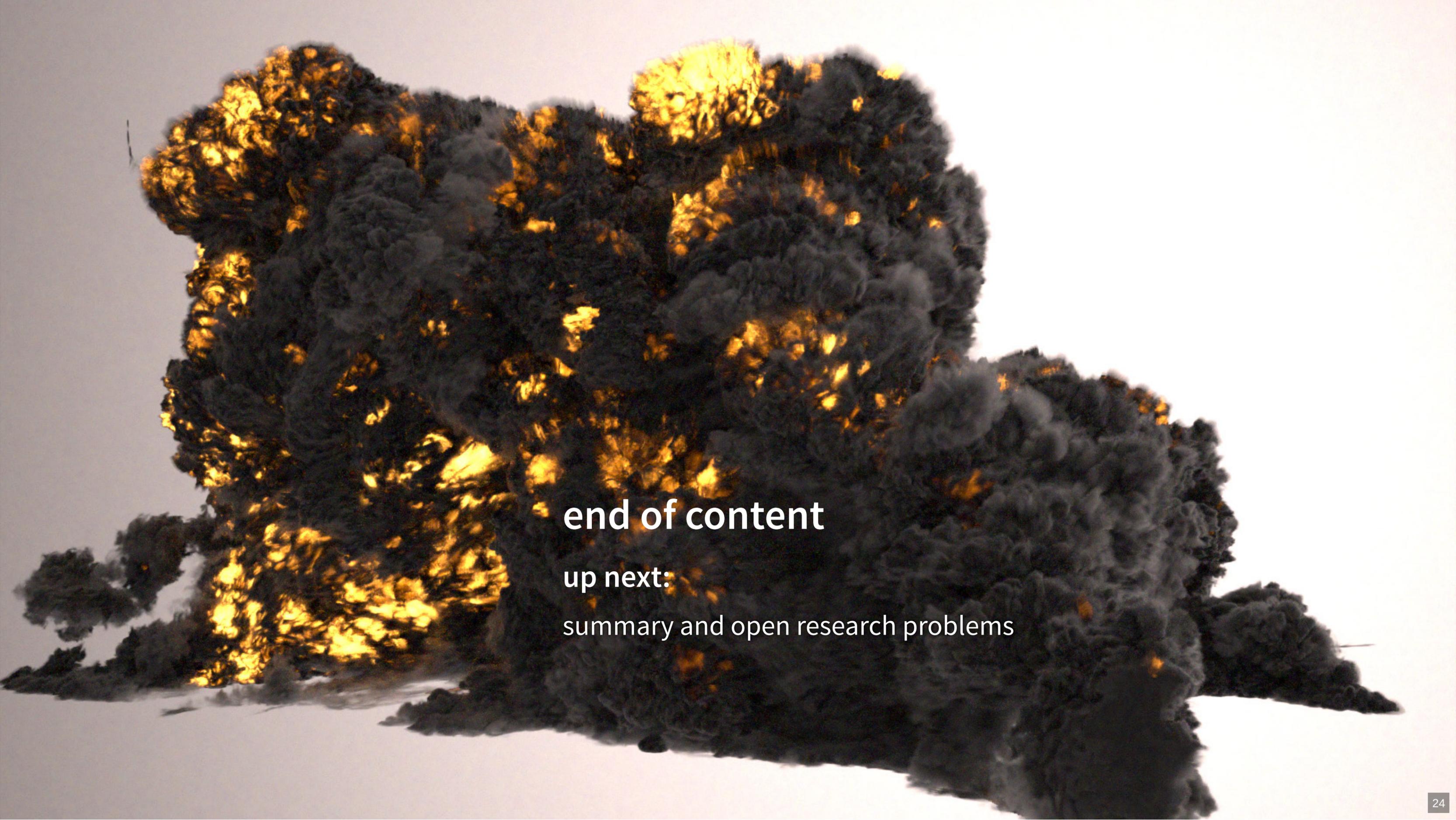
- ▶ reason: NEE cannot create paths with end point outside the medium
 - ▶ forward scattering PDF is poor, however, and now it picks up line emission!

emissive media

thin/dense media make a difference

- ▶ need to teach next event estimation about line emission [SHZD17]:





end of content

up next:

summary and open research problems

summary

free flight distance sampling

- ▶ woodcock/delta tracking

transmittance estimation

- ▶ track-length
- ▶ residual ratio
- ▶ free flight versions

path sampling

- ▶ path space formulation
- ▶ summary of advanced methods

acceleration structures

- ▶ for regular tracking
- ▶ for null collisions (bottom-level)

open research problems

null collision algorithms and MIS

- ▶ missing link to integrate into powerful framework
 - ▶ for instance combine with equi-angular sampling
- ▶ can we estimate the PDF?
 - ▶ expectation and division do not commute!

$$X = \frac{f(\bar{\mathbf{x}})}{p(\bar{\mathbf{x}})}$$

open research problems

leverage recent advances in machine learning

- ▶ special purpose denoising
 - ▶ including a volume prior?
- ▶ path guiding for volumes?
 - ▶ importance sampling for multiple vertices?

open research problems

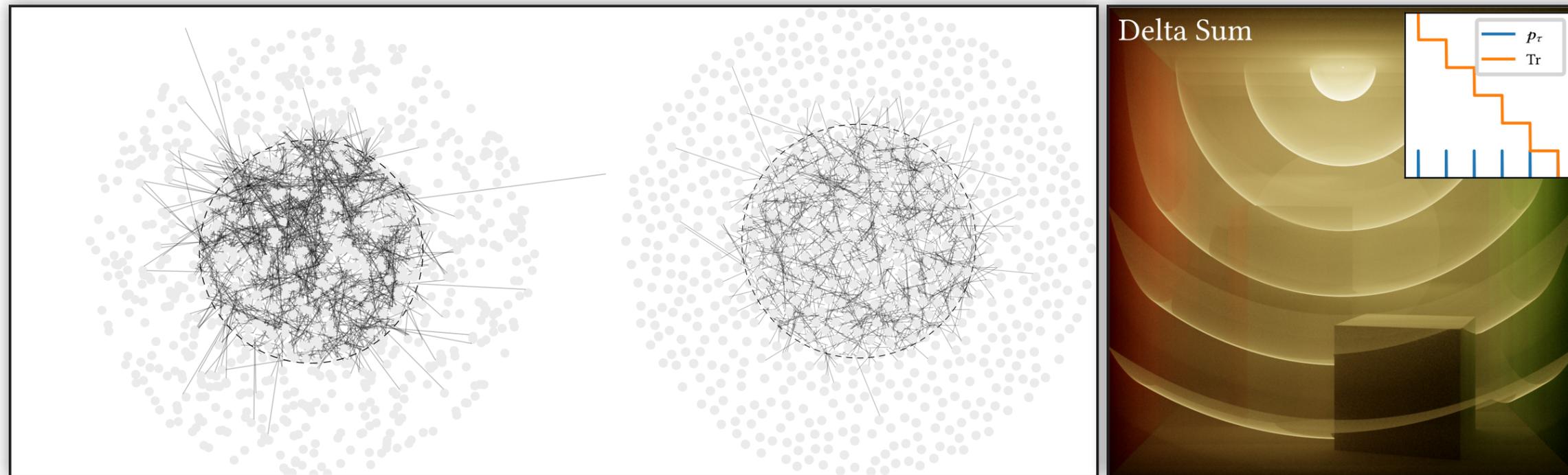
joint handling of surfaces and geometry

- ▶ still often surface transport is handled separately
 - ▶ makes inclusion of all interreflections hard
 - ▶ custom-cut algorithms increase maintenance cost

open research problems

generalisation to correlated scatterers

- ▶ core assumption of exponential path length: uncorrelated particles!
 - ▶ particle repulsion such as in cell growth is very correlated
 - ▶ really, no collision can be found inside the current particle (min distance)
 - ▶ some existing work



[d'Eon 2018, Bitterli et al. 2018]

thank you!

any questions?

acknowledgements:

- ▶ Peter Kutz
 - ▶ for tracing down many of early delta tracking papers
- ▶ Jaroslav Křivánek & reviewers
 - ▶ for feedback on the paper draft
- ▶ Maurizio Nitti
 - ▶ for help w/ fast forward and illustrations

